

# Introduction to differential equations

①

## Second-order linear differential equations.

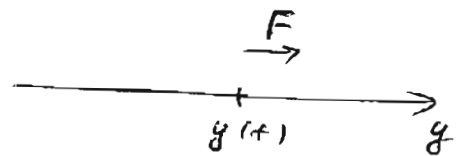
### Def

A second order differential equation is an equation of the form

$$\frac{d^2 y}{dt^2} = f\left(t, y, \frac{dy}{dt}\right)$$

### Example

1)  $m \cdot \frac{d^2 y}{dt^2} = F\left(t, y, \frac{dy}{dt}\right)$



2)



$$\frac{d^2 y}{dt^2} = -g, \quad y(t_0) = y_0, \quad y'(t_0) = y_0'$$

Initial value problem:

Find a function  $y(t)$  such that

$$\begin{cases} \frac{d^2 y}{dt^2} = f\left(t, y, \frac{dy}{dt}\right), \\ y(t_0) = y_0 \\ y'(t_0) = y_0' \end{cases}$$

Def

(2)

Linear differential equation  
of second order

$$\frac{dy^2}{dt^2} + p(t) \frac{dy}{dt} + q(t)y = g(t)$$

- non homogeneous

$$\frac{dy^2}{dt^2} + p(t) \frac{dy}{dt} + q(t)y = 0 \quad (*)$$

- homogeneous,

Thm (Existence and uniqueness)

Suppose  $p(t)$  and  $q(t)$  are continuous on the interval  $(\alpha, \beta)$ ,  $-\infty \leq \alpha < \beta \leq +\infty$ ,  $t_0 \in (\alpha, \beta)$ . Then there exists one, and only one function on  $(\alpha, \beta)$  such that  $y(t_0) = y_0$ ,  $y'(t_0) = y'_0$ , and  $(*)$  holds.

Corollary

If  $y(t)$  is a solution of  $(*)$ ,

$$y(t_0) = y'(t_0) = 0 \text{ then } y(t) \equiv 0.$$

Example

$y(t)$  is a solution of  $(*)$ , for  $t \in \mathbb{R}$ ,  
 $y(\frac{1}{n}) = 0 \quad \forall n \in \mathbb{N}$ . Find  $y(t)$ .

Solution:  $y \equiv 0$ , since  $y(0) = 0$  (by cons),  $y'(0) = 0$ .

## Important remark

(3)

(\*) can be rewritten as

$$L(y) = 0, \text{ where}$$

$L: C^2(\alpha, \beta) \rightarrow C^0(\alpha, \beta)$  - a linear operator,

$$L(y) = y'' + p(t)y' + q(t)y,$$

$C^2(\alpha, \beta) = \{ f: (\alpha, \beta) \rightarrow \mathbb{R} \mid \exists f'' \text{ and } f'' \text{ is continuous on } (\alpha, \beta) \}$

$C^0(\alpha, \beta) = \{ f: (\alpha, \beta) \rightarrow \mathbb{R} \mid f \text{ is continuous} \}$ ,

Since

$$\begin{aligned} L(y_1 + y_2) &= (y_1 + y_2)'' + p(t)(y_1 + y_2)' + q(t)(y_1 + y_2) \\ &= y_1'' + p(t)y_1' + q(t)y_1 + \\ &\quad + y_2'' + p(t)y_2' + q(t)y_2 = \\ &= L(y_1) + L(y_2), \end{aligned}$$

and  $L(cy) = (cy)'' + p(t)(cy)' + q(t)(cy) =$   
 $= cL(y),$

$L$  is a linear operator,

### Example

Consider an operator  $L(y) = y'' + t^2 y'$ ,

$$\text{Then } L(e^t) = e^t + t^2 e^t$$

$$L(e^{-t}) = e^{-t} - t^2 e^{-t}$$

$$L(t) = t^2$$

$$L(t^2) = 2 + 2t^3, \quad L(1) = 0$$

$y$  is solution of (\*)  $\Leftrightarrow L(y) = 0$ ,

(4)

### Remark

Solutions of (\*) =  $\text{Ker } L$ .

(Def:  $\text{Ker } L = \{y \in C^2(I, \mathbb{R}) \mid Ly = 0\}$ )

### Lemma

The space of solutions of (\*) is a linear space.

### Proof

$L(y_1) = 0, L(y_2) = 0 \Rightarrow L(y_1 + y_2) = L(y_1) + L(y_2) = 0$ ,  
so  $y_1 + y_2$  is a solution too.

$L(cy_1) = cL(y_1) = 0 \Rightarrow cy_1$  is a solution too  $\square$ .

### Example

$$y'' + y = 0$$

$y_1(t) = \cos t$  is a solution

$y_2(t) = \sin t$  is a solution

$y(t) = C_1 \cos t + C_2 \sin t$  is a solution  $\forall C_1, C_2 \in \mathbb{R}$ .

### Proposition

Any solution of  $y'' + y = 0$  has the form

$$C_1 \cos t + C_2 \sin t.$$

Proof

Assume that  $y(t)$  is a solution of the equation

$$y'' + y = 0$$

Let  $y(0) = y_0$ ,  $y'(0) = y_0'$ , and take

$$\tilde{y}(t) = y_0 \cos t + y_0' \sin t$$

Then  $\tilde{y}(0) = y_0$

$$\tilde{y}'(0) = -y_0 \sin 0 + y_0' \cos 0 = y_0'$$

But  $\exists$  only one solution such that

at 0 it is  $y_0$  and its derivative is  $y_0'$ , so

$$y(t) \equiv \tilde{y}(t) \quad \square.$$

Theorem

Let  $y_1(t)$  and  $y_2(t)$  be two solutions of (\*) on  $(\alpha, \beta)$ ,  ~~$t_0 \in (\alpha, \beta)$~~  and

$$\det \begin{pmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{pmatrix} \equiv y_1(t)y_2'(t) - y_1'(t)y_2(t)$$

does not vanish  $\forall t \in (\alpha, \beta)$ .

Then

$$y(t) = C_1 y_1(t) + C_2 y_2(t)$$

is a general solution of (\*).

Def

An expression  $\det \begin{pmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{pmatrix}$

(6)

is called the Wronskian of  $y_1$  and  $y_2$ .

Notation:  $W(t) = W[y_1, y_2](t)$ .

Proof

Let  $y(t)$  be a solution of (x).

Take any  $t_0 \in (\alpha, \beta)$ , and let  $y_0, y_0'$  be the values of  $y(t_0)$  and  $y'(t_0)$ .

$$\begin{cases} c_1 y_1(t_0) + c_2 y_2(t_0) = y_0 \\ c_1 y_1'(t_0) + c_2 y_2'(t_0) = y_0' \end{cases} \begin{array}{l} \times y_2'(t_0) \\ - \times y_2(t_0) \end{array}$$

$$c_1 W[y_1, y_2](t_0) = y_0 y_2'(t_0) - y_0' y_2(t_0),$$

$$c_1 = \frac{y_0 y_2'(t_0) - y_0' y_2(t_0)}{W[y_1, y_2](t_0)}$$

Similarly,

$$c_2 = \frac{y_0' y_1(t_0) - y_0 y_1'(t_0)}{W[y_1, y_2](t_0)}.$$

$$\text{Set } \varphi(t) = c_1 y_1(t) + c_2 y_2(t).$$

$$\text{Then } \varphi(t_0) = y_0$$

$$\varphi'(t_0) = y_0', \text{ so } \varphi(t) \equiv y(t)$$



## Theorem

(7)

Let  $p(t), q(t)$  be continuous on  $(\alpha, \beta)$ , and  $y_1, y_2$  be two solutions of  $(*)$ .

Then either  $W[y_1, y_2] \equiv 0$  or

$$W[y_1, y_2](t) \neq 0 \quad \forall t \in (\alpha, \beta),$$

## Proof

$$W[y_1, y_2](t) = y_1(t)y_2'(t) - y_2(t)y_1'(t), \text{ so}$$

$$\begin{aligned} \frac{d}{dt} W(t) &= \cancel{y_1'(t)y_2'(t)} + y_1(t)y_2''(t) - \\ &\quad - \cancel{y_2'(t)y_1'(t)} - y_2(t)y_1''(t) = \end{aligned}$$

$$\begin{aligned} &= y_1(t)(-p(t)y_2'(t) - q(t)y_2(t)) - \\ &\quad - y_2(t)(-p(t)y_1'(t) - q(t)y_1(t)) = \end{aligned}$$

$$= -p(t)W(t)$$

Take any  $t_0 \in (\alpha, \beta)$ . Then

$$W[y_1, y_2](t) = W[y_1, y_2](t_0) \cdot \underbrace{e^{-\int_{t_0}^t p(s) ds}}_{x_0},$$

therefore either  $W(t) \equiv 0$  or

$$W(t) \neq 0 \quad \forall t \in (\alpha, \beta).$$

□

## Remark

(8)

If  $y_1 \equiv 0$  then  $W[y_1, y_2] \equiv 0$ .

If  $y_1 = c y_2$  then  $W[y_1, y_2] \equiv 0$ .

## Def

Functions  $y_1(t), y_2(t)$  are linearly dependent if  $y_1 = c y_2$  (or  $y_2 = c y_1$ ).

## Theorem

If  $y_1, y_2$  are two solutions, and at some point  $t_0 \in (\alpha, \beta)$   $W(t_0) = 0$  then

$y_1$  and  $y_2$  are linearly dependent.

## Proof

$W[y_1, y_2](t_0) = 0 \Rightarrow W(t) \equiv 0$ , so

$$y_1(t) y_2'(t) \equiv y_1'(t) y_2(t).$$

If  $y_1(t) y_2(t) \neq 0$  for  $\alpha < t < \beta$  then

$$\frac{y_2'(t)}{y_2(t)} = \frac{y_1'(t)}{y_1(t)}$$

$$(\ln |y_2(t)|)' = (\ln |y_1(t)|)'$$

$$\ln |y_2(t)| = \ln |y_1(t)| + \tilde{c}$$

$$|y_2(t)| = e^{\tilde{c}} \cdot |y_1(t)|$$

$$y_2(t) = c y_1(t).$$



If  $\exists t^* \text{ s.t. } y_1(t^*) = 0$  then

$$y_1'(t^*) y_2(t^*) = 0$$

If  $y_1'(t^*) = 0$  then  $y_1 \equiv 0$ .

If  $y_1'(t^*) \neq 0$  then  $y_2(t^*) = 0$ ,

$$\text{and } y_2'(t^*) = \left[ \frac{y_2'(t^*)}{y_1'(t^*)} \right] \cdot y_1'(t^*).$$

Consider  $\varphi(t) = \left[ \frac{y_2'(t^*)}{y_1'(t^*)} \right] \cdot y_1(t)$  - solution of (\*).

We have  $\varphi(t^*) = 0 = y_2(t^*)$

$$\varphi'(t^*) = y_2'(t^*),$$

then  $\varphi(t) \equiv y_2(t)$ , so

$y_1$  and  $y_2$  are linearly dependent  $\square$

Example

1)  ~~$e^{at}, e^{bt}$~~   $e^{at}, e^{bt}$  are linearly independent if  $a \neq b$ .

2)  $t, t^3$  — " —

3)  $\cos t, \sin t$  — " —

4)  $t^2, t \cdot |t|$  are linearly independent on  $\mathbb{R}$ , but  $W(t) \equiv 0$ . These functions are not solutions of (\*) for any  $p(t), q(t)$ ! (the same)