

Properties of solutions

Assume that  $\bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$  and  $\bar{y} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$  are solutions,

$$\begin{cases} \dot{x}_1 = a_{11}x_1 + \dots + a_{1n}x_n \\ \vdots \\ \dot{x}_n = a_{n1}x_1 + \dots + a_{nn}x_n \end{cases}, \quad \begin{cases} \dot{y}_1 = a_{11}y_1 + \dots + a_{1n}y_n \\ \vdots \\ \dot{y}_n = a_{n1}y_1 + \dots + a_{nn}y_n \end{cases}$$

then 
$$\begin{cases} \frac{d}{dt}(x_1 + y_1) = a_{11}(x_1 + y_1) + a_{12}(x_2 + y_2) + \dots + a_{1n}(x_n + y_n) \\ \vdots \\ \frac{d}{dt}(x_n + y_n) = a_{n1}(x_1 + y_1) + \dots + a_{nn}(x_n + y_n) \end{cases}$$

so  $\bar{x} + \bar{y} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{pmatrix}$  is also a solution.

Also,  $\forall c \in \mathbb{R}$   $c\bar{x} = \begin{pmatrix} cx_1 \\ \vdots \\ cx_n \end{pmatrix}$  is a solution.

(i)  $\bar{x} + \bar{y} = \bar{y} + \bar{x}$

(ii)  $\bar{x} + (\bar{y} + \bar{z}) = (\bar{x} + \bar{y}) + \bar{z}$

(iii)  $\bar{0}(t) \equiv \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$  is a solution, and if  $\bar{x}$  is a solution, then  $\bar{x} + \bar{0} = \bar{0} + \bar{x} = \bar{x}$ .

(iv) If  $\bar{x}$  is a solution then  $-\bar{x} = \begin{pmatrix} -x_1 \\ \vdots \\ -x_n \end{pmatrix}$  is a solution, and  $\bar{x} + (-\bar{x}) \equiv \bar{0}$

(v)  $1 \cdot \bar{x} = \bar{x}$

(vi) For any numbers  $a, b \in \mathbb{R}$  (or  $a, b \in \mathbb{C}$ )  $(a+b)\bar{x} = a\bar{x} + b\bar{x}$

$$(vii) \alpha(\bar{x} + \bar{y}) = \alpha\bar{x} + \alpha\bar{y}$$

$$(viii) (\alpha + \beta)\bar{x} = \alpha\bar{x} + \beta\bar{x}$$

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### Def

A set  $L$  of elements called "vectors" ( $\bar{x}, \bar{y}, \bar{z}, \dots$ ) is a linear space if vectors can be multiplied by a number (so that  $\forall \alpha \in \mathbb{R}$   $\alpha\bar{x}$  is also a vector), and an addition of vectors is defined (so  $\bar{x} + \bar{y}$  is also a vector), and properties (i) - (viii) above hold.

### Examples

1) Consider  $\mathbb{R}^2 = \{(x, y) \mid x, y \in \mathbb{R}\}$ , where

$$(x, y) + (z, w) = (x+z, y+w), \quad \alpha(x, y) = (\alpha x, \alpha y).$$

$$2) \bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \quad x_i \in \mathbb{R},$$

$$\bar{x} + \bar{y} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{pmatrix}, \quad \alpha\bar{x} = \begin{pmatrix} \alpha x_1 \\ \vdots \\ \alpha x_n \end{pmatrix}.$$

4) Consider all continuous functions

$$\bar{x} = x(t), \quad t \in [0, 1], \quad \bar{x} + \bar{y} = x(t) + y(t) : [0, 1] \rightarrow \mathbb{R},$$

$$\alpha\bar{x} = \alpha x(t) : [0, 1] \rightarrow \mathbb{R}$$

$$\bar{0} \equiv 0$$

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$$5) a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = 0$$

The space of all solutions  $y(t)$  is a vector space:

$y_1(t), y_2(t)$  - are solutions  $\Rightarrow$

$y_1 + y_2$  is a solution,  $\alpha y_1$  is a solution.

6) Let  $L$  be the space of all matrices  $2 \times 2$ ,

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}, \quad B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix},$$

$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ b_{21} + a_{21} & a_{22} + b_{22} \end{pmatrix}, \quad cA = \begin{pmatrix} ca_{11} & ca_{12} \\ ca_{21} & ca_{22} \end{pmatrix}$$

7)  $\dot{\bar{x}} = A(t)\bar{x}$ ,

the space of solutions  $\bar{x}(t)$  is a vector space.

Def

A set of vectors  $\bar{x}^1, \bar{x}^2, \dots, \bar{x}^n$  is said to span a linear space  $L$  if any vector  $\bar{v} \in L$  can be represented as

$$\bar{v} = c_1 \bar{x}^1 + c_2 \bar{x}^2 + \dots + c_n \bar{x}^n, \text{ for some numbers } c_i \in \mathbb{R}.$$

Def

The dimension of a vector space  $L$  ( $\dim L$ ) is the fewest number of linearly independent vectors  $\bar{x}^1, \dots, \bar{x}^n$  which span  $L$ .

Def

$\bar{x}^1, \dots, \bar{x}^n$  are linearly independent if  $C_1 \bar{x}^1 + \dots + C_n \bar{x}^n = \bar{0} \Rightarrow C_1 = C_2 = \dots = C_n = 0$ .

Theorem 1 (Existence and uniqueness)

$\dot{\bar{x}} = A \bar{x}$ ,  ~~$A$  is a constant matrix~~  $A$  is a constant matrix

There exists one, and only one solution of the initial-value problem

$\frac{d}{dt} \bar{x} = A \bar{x}$ ,  $\bar{x}(0) = \begin{pmatrix} x_1^0 \\ \vdots \\ x_n^0 \end{pmatrix}$ ,

and this solution exists for all  $t \in \mathbb{R}$ .

Thm 2

All solutions of the system  $\dot{\bar{x}} = A \bar{x}$ ,  $\bar{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ , form a linear space of dimension  $n$ .

The idea of the proof:

Consider solutions  $\bar{x}^1, \bar{x}^2, \dots, \bar{x}^n$  with initial conditions  $\bar{x}^1(0) = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ ,  $\bar{x}^2(0) = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}$ ,  $\dots$ ,  $\bar{x}^n(0) = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$ .

These solutions are linearly independent,  
and if  $\bar{y}(t) = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$  is a solution, then

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Consider  $y_1(0) \bar{x}^1 + y_2(0) \bar{x}^2 + \dots + y_n(0) \bar{x}^n$ .

This is also a solution, and its initial conditions are the same as for  $y(t)$ , so

$$y(t) = y_1(0) \bar{x}^1 + \dots + y_n(0) \bar{x}^n. \quad \square$$